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► To cite this version:

Artur Pessoa, Ruslan Sadykov, Eduardo Uchoa. An improved Branch-Cut-and-Price algorithm for heterogeneous vehicle routing problems. VeRoLog 2017 - Annual Workshop of the EURO Working Group on Vehicle Routing and Logistics optimization, Jul 2017, Amsterdam, Netherlands. hal-01676022

HAL Id: hal-01676022

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An improved Branch-Cut-and-Price Algorithm for Heterogeneous Vehicle Routing Problems

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Verolog 2017
Amsterdam, July 11

Heterogeneous Vehicle Routing

Set I of n customers, each $i \in I$ with demand d_i .

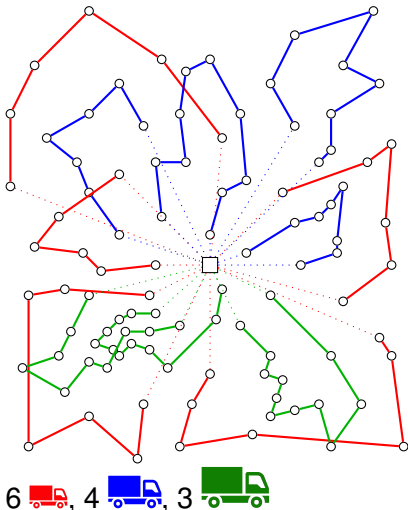
Set U of vehicle types, each $u \in U$ has a depot with K_u vehicles of capacity Q_u , with fixed cost f_u and travel costs c_a^u for each edge a .

Objective: minimize the total fixed and travel cost.

Variants

- ▶ Multi-depot VRP
- ▶ Site-dependent VRP

Instance HVRPFV-20-100



Optimum **4760.68** (BKS 4761.26)

Set partitioning (master) formulation

- ▶ R_u — set of q -routes feasible for a vehicle of type u
- ▶ a_i^r — number of times that customer i appears in route r .
- ▶ c_r — cost of route r .
- ▶ **Binary variable** $\lambda_u^r = 1$ if and only if a vehicle of type u uses route r

$$\begin{aligned} \min \quad & \sum_{u \in U} \sum_{r \in R_u} c_r \lambda_r \\ & \sum_{u \in U} \sum_{r \in R_u} a_i^r \lambda_r = 1, \quad \forall i \in I, \\ & \sum_{r \in R_u} \lambda_r \leq K_u, \quad \forall u \in U, \\ & \lambda_r \in \{0, 1\}, \quad \forall r \in R_u, \forall u \in U. \end{aligned}$$

Pricing subproblem for a vehicle type

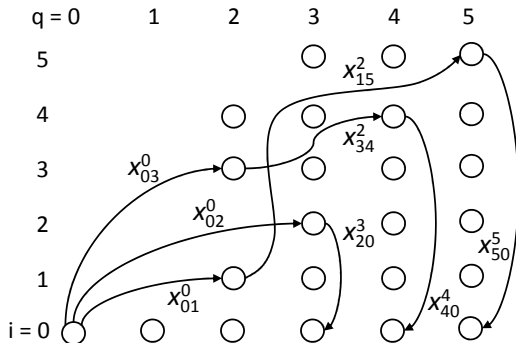
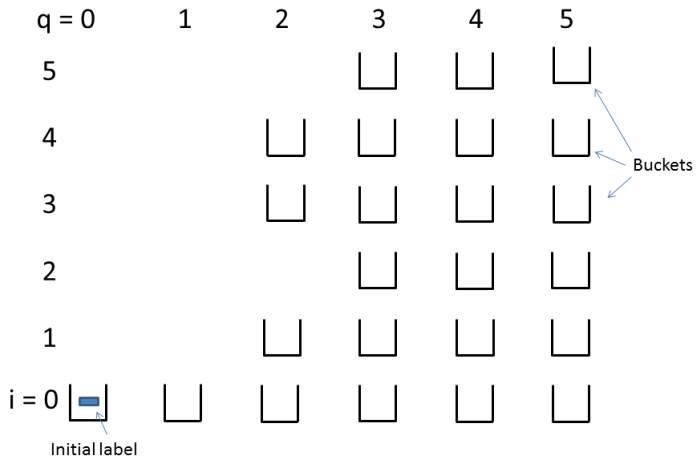
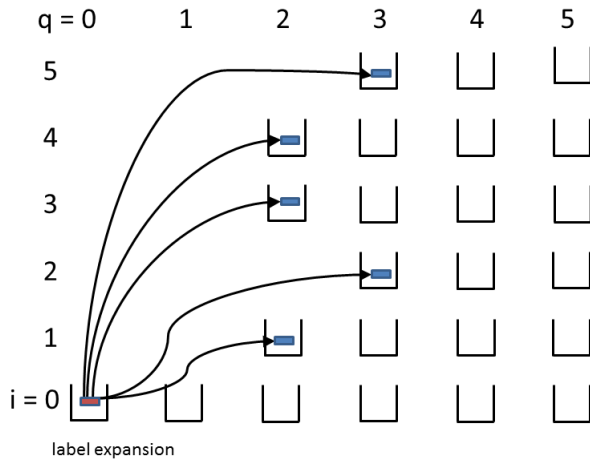


Figure: $|I| = Q = 5$, $d_1 = d_3 = d_4 = 2$, $d_2 = d_5 = 3$; routes 0-1-5-0, 0-2-0, 0-3-4-0 are shown

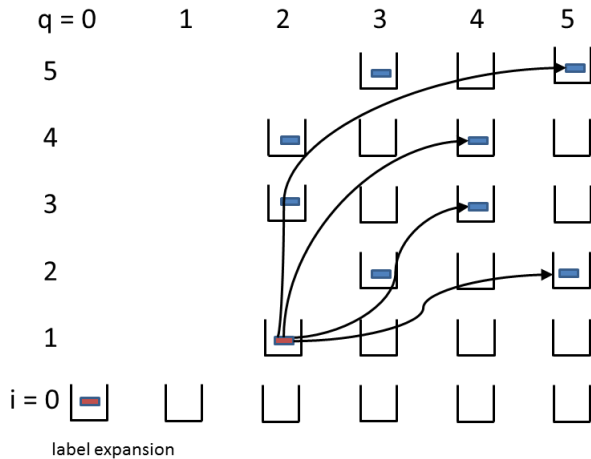
The labeling algorithm



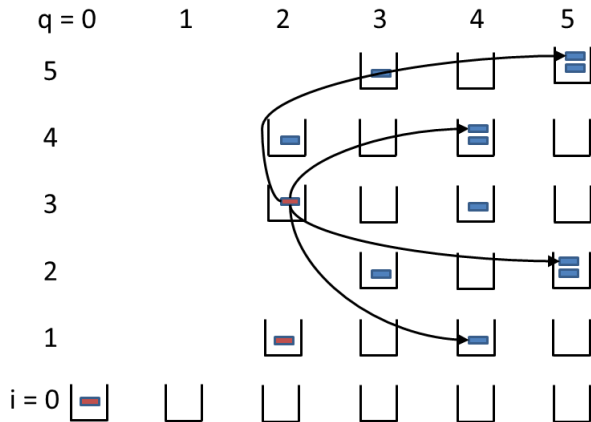
The labeling algorithm



The labeling algorithm

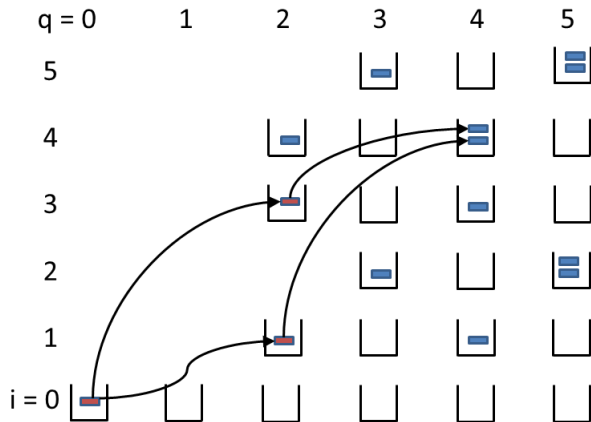


The labeling algorithm



Do both labels need to be kept in bucket $(4, 4)$?

The labeling algorithm



The labels represent partial paths 0-1-4 and 0-3-4

Subset Row Cuts (SRCs)

Given $C \subseteq V_+$ and a multiplier p , the (C, p) -Subset Row Cut is:

$$\sum_{u \in U} \sum_{r \in R_u} \left\lfloor p \sum_{i \in C} a_i^r \right\rfloor \lambda_r \leq \lfloor p|C| \rfloor$$

Special case of **Chvátal-Gomory rank-1 cuts** obtained by rounding of $|C|$ constraints in the master

Each cut adds **an additional resource** in the shortest path pricing problem

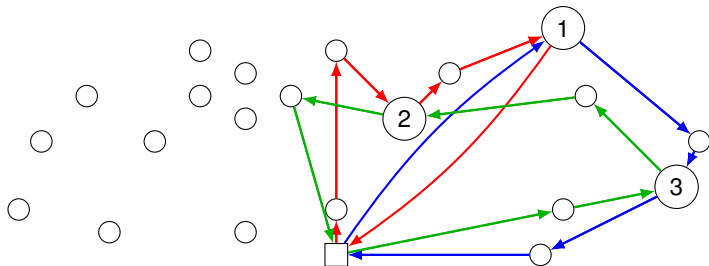


Mads Jepsen and Bjorn Petersen and Simon Spoorendonk and David Pisinger (2008).

Subset-Row Inequalities Applied to the Vehicle-Routing Problem with Time Windows.

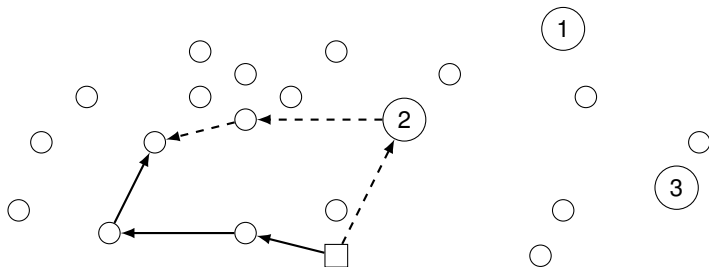
Operations Research, 56(2):497–511.

Example of 3-Subset Row Cut, $|C| = 3$, $p = \frac{1}{2}$



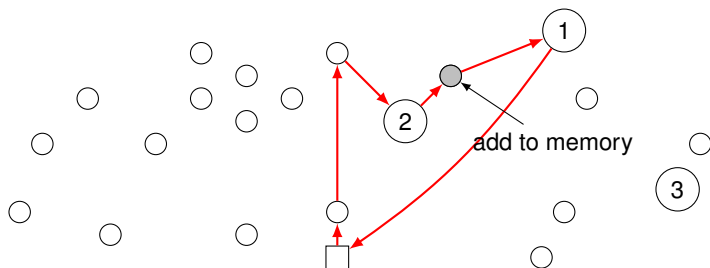
If $\lambda_1 = 0.5$, $\lambda_2 = 0.5$, and $\lambda_3 = 0.5$, cut $C = \{1, 2, 3\}$ is violated.

Example of 3-Subset Row Cut, $|C| = 3$, $p = \frac{1}{2}$



Less possibilities for domination after adding the cut.

Example of 3-Subset Row Cut, $|C| = 3$, $p = \frac{1}{2}$



Concept of **limited memory cuts** [Pecin et al., 2017b].

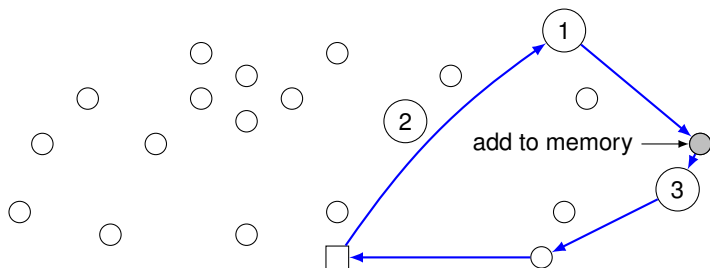


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Mathematical Programming Computation, 9(1):61–100.

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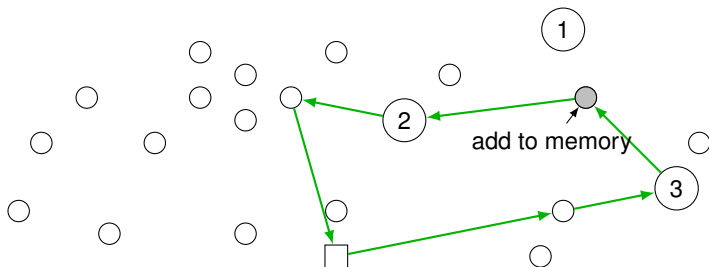


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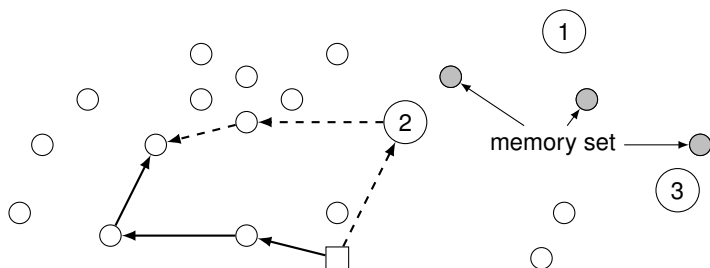


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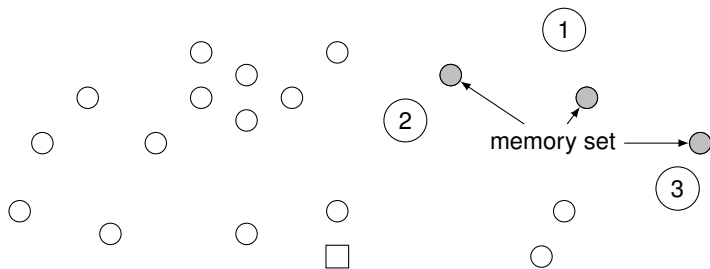
Mathematical Programming Computation, 9(1):61–100.

Example of 3-Subset Row Cut, $|C| = 3$, $p = \frac{1}{2}$



Dashed partial path “forgot” the cut (cut state in the label is 0)
 \Rightarrow larger domination probability.

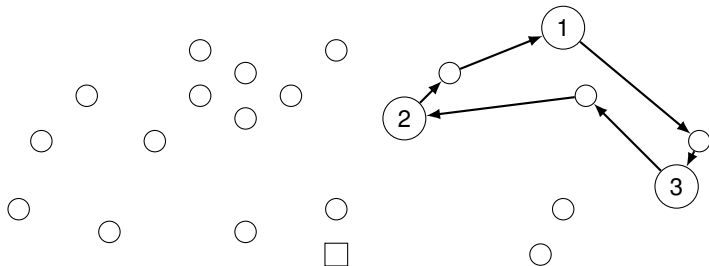
Example of 3-Subset Row Cut, $|C| = 3$, $p = \frac{1}{2}$



Different memory sets

- Node memory

Example of 3-Subset Row Cut, $|C| = 3$, $p = \frac{1}{2}$



Different memory sets

- ▶ Node memory
- ▶ Arc memory [Pecin et al., 2017a]

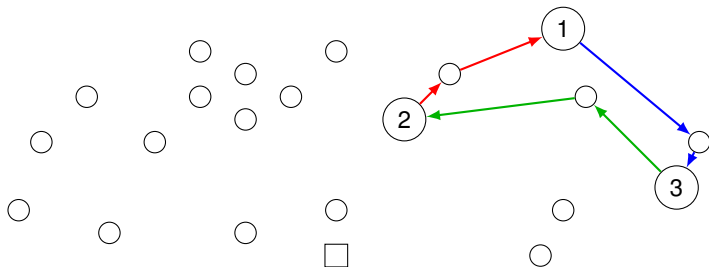


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New enhancements for the exact solution of the vehicle routing problem with time windows.

INFORMS Journal on Computing, 29(3):489–502.

Example of 3-Subset Row Cut, $|C| = 3$, $p = \frac{1}{2}$



Different memory sets

- ▶ Node memory
- ▶ Arc memory [Pecin et al., 2017a]
- ▶ Subproblem dependent memory (this work)



Pecin, D., Contardo, C., Desaulniers, G., and Uchoa, E. (2017a).

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Arbitrary cuts of Rank 1

Rounding using a **vector** p instead of single value:

$$\sum_{u \in U} \sum_{r \in R_u} \left\lfloor \sum_{i \in C} p_i a_i^r \right\rfloor \lambda_r \leq \left\lfloor \sum_{i \in C} p_i \right\rfloor$$

All facet-defining vectors p for cuts up to 5 rows
[Pecin et al., 2017c]:

- ▶ $|C| = 1, p = (\frac{1}{2})$
- ▶ $|C| = 3, p = (\frac{1}{2}, \frac{1}{2}, \frac{1}{2})$
- ▶ $|C| = 4, p = (\frac{2}{3}, \frac{1}{3}, \frac{1}{3}, \frac{1}{3})$
- ▶ $|C| = 5, p = (\frac{1}{3}, \frac{1}{3}, \frac{1}{3}, \frac{1}{3}, \frac{1}{3})$
- ▶ $|C| = 5, p = (\frac{2}{4}, \frac{2}{4}, \frac{1}{4}, \frac{1}{4}, \frac{1}{4})$
- ▶ $|C| = 5, p = (\frac{3}{4}, \frac{1}{4}, \frac{1}{4}, \frac{1}{4}, \frac{1}{4})$
- ▶ $|C| = 5, p = (\frac{3}{5}, \frac{2}{5}, \frac{2}{5}, \frac{1}{5}, \frac{1}{5})$
- ▶ $|C| = 5, p = (\frac{1}{2}, \frac{1}{2}, \frac{1}{2}, \frac{1}{2}, \frac{1}{2})$
- ▶ $|C| = 5, p = (\frac{2}{3}, \frac{2}{3}, \frac{1}{3}, \frac{1}{3}, \frac{1}{3})$
- ▶ $|C| = 5, p = (\frac{3}{4}, \frac{3}{4}, \frac{2}{4}, \frac{2}{4}, \frac{1}{4})$



Pecin, D., Pessoa, A., Poggi, M., Uchoa, E., and Santos, H. (2017).

Limited memory rank-1 cuts for vehicle routing problems.

Operations Research Letters, 45(3):206 – 209.

Extended Capacity Cuts

Definition

An Extended Capacity Cut (ECC) [Pessoa et al., 2009] over subset C of customers is any inequality valid for $P(C)$, the polyhedron given by the convex hull of the 0 – 1 solutions of

$$\sum_{u \in U} \left(\sum_{a \in \delta_u^-(C)} \sum_{q=1}^Q dx_a^q - \sum_{a \in \delta_u^+(C)} \sum_{q=0}^{Q-1} dx_a^q \right) = d(C)$$



Pessoa, Artur and Uchoa, Eduardo and Poggi, Marcus (2009).

A robust branch-cut-and-price algorithm for the heterogeneous fleet vehicle routing problem.

Networks, 54(4):167–177.

Homogeneous Extended Capacity Cuts

$$y^{m,q} = \sum_{a^q \in \delta_u^-(C)} x_a^q, \quad z^q = \sum_{a^q \in \delta_u^+(C)} x_a^{m,q}, \quad (q = 0, \dots, Q).$$

Definition

A Homogeneous Extended Capacity Cut (HECC) over set C of customers is any inequality valid for the polyhedron given by the convex hull of the integral solutions of

$$\sum_{u \in U} \left(\sum_{q=1}^Q dy^{m,q} - \sum_{q=0}^{Q-1} dz^{m,q} \right) = d(C). \quad (1)$$

Separation

- ▶ Cuts obtained by applying integer rounding of (1).
- ▶ Heuristic separation of [Pessoa et al., 2009] is used.

Labeling algorithm enhancements

- ▶ **ng-routes** to impose partial elementarity [Baldacci et al., 2011].
- ▶ **Bi-directional** labelling [Righini and Salani, 2006]
- ▶ **Reduced cost fixing** of subproblem arc variables x [Irnich et al., 2010]



Baldacci, R., Mingozi, A., and Roberti, R. (2011).

New route relaxation and pricing strategies for the vehicle routing problem.

Operations Research, 59(5):1269–1283.



Righini, G. and Salani, M. (2006).

Symmetry helps: Bounded bi-directional dynamic programming for the elementary shortest path problem with resource constraints.

Discrete Optimization, 3(3):255 – 273.



Irnich, S., Desaulniers, G., Desrosiers, J., and Hadjar, A. (2010).

Path-reduced costs for eliminating arcs in routing and scheduling.

INFORMS Journal on Computing, 22(2):297–313.

Elementary routes enumeration

We try to enumerate all elementary routes whose reduced cost is smaller than the current gap [Baldacci et al., 2008], possibly to a pool [Contardo and Martinelli, 2014].

This work contributions

- ▶ **Subproblem dependent** enumeration
- ▶ If succeeded, a subproblem passes to the **enumerated state**:
 - ▶ Pricing is performed by **inspection**
 - ▶ **Cut coefficients** of columns in the master are **lifted**



Baldacci, R., Christofides, N., and Mingozzi, A. (2008).

An exact algorithm for the vehicle routing problem based on the set partitioning formulation with additional cuts.

Mathematical Programming, 115:351–385.

Lifting of cuts in enumerated state

Rank-1 cuts

Limited memory is extended to **full memory**

Homogeneous Extended Capacity Cuts

Integer rounding of

$$\sum_{u \in EU} \sum_{r \in R_u} d_r(C) \lambda_r + \sum_{u \in U \setminus EU} \left(\sum_{q=1}^Q dy^{m,q} - \sum_{q=0}^{Q-1} dz^{m,q} \right) = d(C).$$

For a particular rounding multiplier and $EU = U$ (all subproblems are in the enumerated state), equivalent to Strong Capacity Cuts [Baldacci et al., 2008].

Other enhancements

- ▶ Heuristic pricing (keeping one label per bucket)
- ▶ Automatic dual price smoothing stabilization [Pessoa et al., 2017].
- ▶ Rollback mechanism [Pecin et al., 2017b]



Pessoa, A., Sadykov, R., Uchoa, E., and Vanderbeck, F. (2017).

Automation and combination of linear-programming based stabilization techniques in column generation.

INFORMS Journal on Computing, (Forthcoming).

Branching

Strong branching [Pecin et al., 2017b]

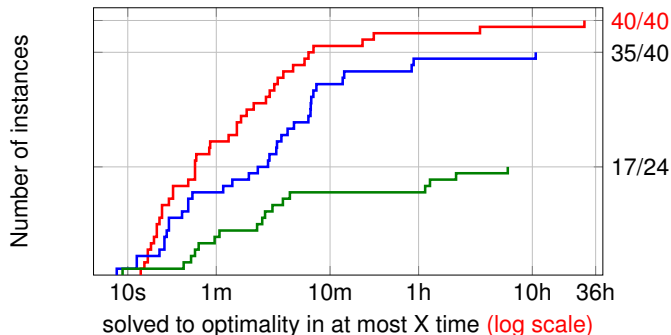
- ▶ Multi-strategy
- ▶ Branching history (**pseudo-costs**)
- ▶ Multi-phase

Branching strategies

- ▶ Number of vehicles
- ▶ Assignment of customers to vehicle types
- ▶ Participation of arcs in routes

Results for classic Heterogeneous VRP instances

40 instances with 50-100 customers by [Taillard, E. D., 1999]



— Our algorithm — [Baldacci and Mingozzi, 2009] — [Pessoa et al., 2009]



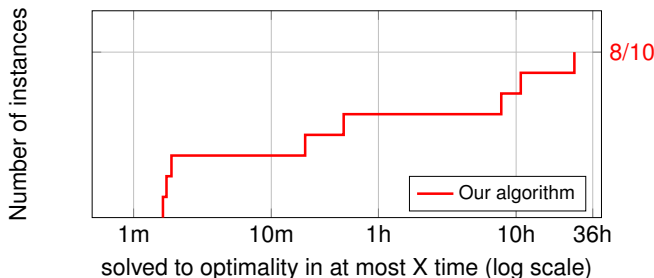
Baldacci, R. and Mingozzi, A. (2009).

A unified exact method for solving different classes of vehicle routing problems.

Mathematical Programming, 120(2):347–380.

Results for larger Heterogeneous VRP instances

10 instances with 100-200 customers [Brandao, 2011]



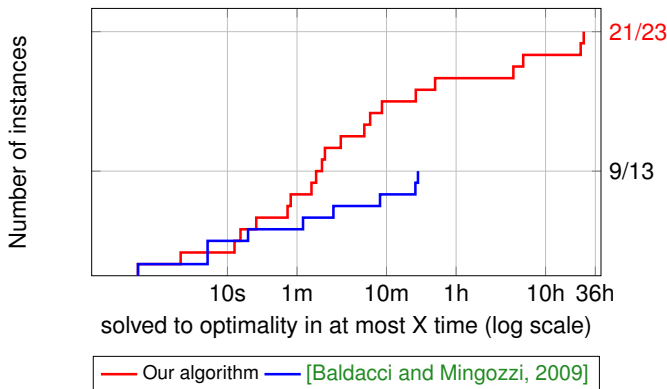
Brandao, J. (2011).

A tabu search algorithm for the heterogeneous fixed fleet vehicle routing problem.

Computers and Operations Research, 38(1):140 – 151.

Results for standard Site-Dependent VRP instances

Instances with 27-324 customers by [Cordeau and Laporte, 2001]

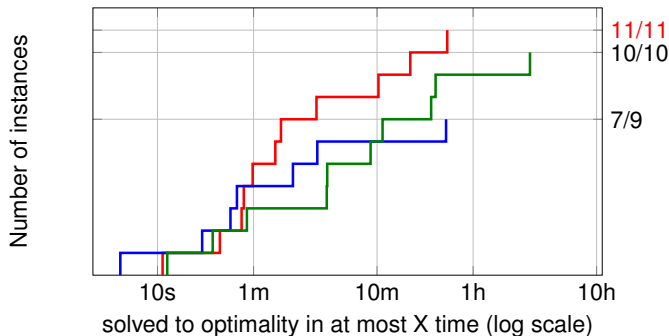


Largest solved instance has **216 customers**

[Baldacci and Mingozzi, 2009] solved only 1 of 5 instances with 100 customers and more

Results for standard Multi-Depot VRP instances

Instances with 50–360 customers [Cordeau et al., 1997]



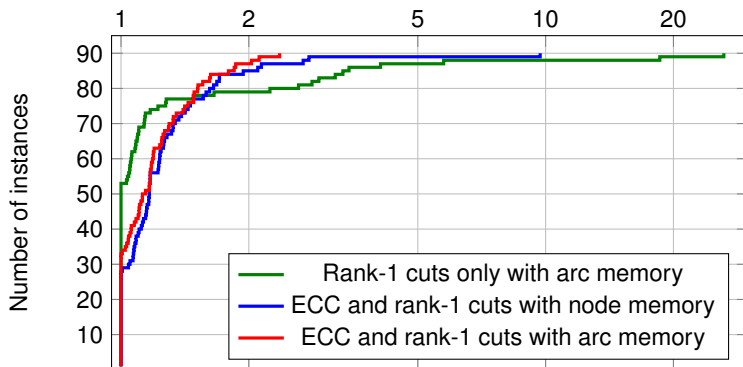
Contardo, C. and Martinelli, R. (2014).

A new exact algorithm for the multi-depot vehicle routing problem under capacity and route length constraints.

Discrete Optimization, 12:129 – 146.

Impact of Extended Capacity Cuts

Cuts	Rank-1 cuts memory	Root gap	Root time	Nodes num.	Solved	Total time
R1C only	arc, sp.dep	0.323%	93	67.8	87/90	181
R1C+ECC	node, sp.dep	0.133%	106	38.7	86/90	178
R1C+ECC	arc, sp.dep	0.105%	113	29.6	88/90	170



for which variant is at most X times slower than the best

Improved Best Known Solutions

Problem	Instance	Size	Previous BKS	Reference	Improved value
HVRP	BrandaoN1fsm	150	2212.77	[SPUS12]	2211.63
	BrandaoN1hd	150	2234.13	[S16]	2233.90
	BrandaoN2fsm	199	2823.75	[SPUS12]	2810.20
	BrandaoN2hd	199	2859.82	[S16]	2851.94
	c100_20fsmf	100	4032.81	[SPUS12]	4029.61
	c100_20hvrp	100	4761.26	[SPUS12]	4760.68
MDVRP	n200-k16-3-80	200	1757.86	[BM09]	1756.48
SDVRP	p16	216	3393.55	[CM12]	3393.31
	p18	324	4751.27	[CM12]	4747.75 ¹
	p21	209	1263.71	[CM12]	1260.01

¹ optimality is not proved, other values are optimal

[SPUS12] [Subramanian et al., 2012]

[S16] [Subramanian, 2016]

[BM09] [Baldacci and Mingozzi, 2009]

[CM12] [Cordeau and Maischberger, 2012]

Contributions

- ▶ Large computational improvement over the state-of-the-art algorithms for the problem
- ▶ Showed importance of Extended Capacity Cuts
- ▶ New concept of subproblem dependent memory for rank-1 cuts
- ▶ New concept of “enumerated state” for pricing subproblems
- ▶ New family of lifted Extended Capacity Cuts

Case of multiple and “non-discretizable” resources

Presentation at IFORS in Quebec next week

**A Bucket Graph Based Labelling Algorithm for the RCSP
with Applications to Vehicle Routing**

Case of multiple and “non-discretizable” resources

Presentation at IFORS in Quebec next week

A Bucket Graph Based Labelling Algorithm for the RCSP with Applications to Vehicle Routing

A glimpse of the results

- ▶ Solved 5/9 open VRPTW instances of [Gehring and Homberger, 2002] with 200 customers
- ▶ Solved 6/7 distance-constrained CVRP instances of [Christofides et al., 1979] (CMT) with up to 200 customers
- ▶ Solved all 22 distance-constrained MDVRP instances of [Cordeau et al., 1997] with up to 288 customers
- ▶ Solved 7/10 distance-constrained SDVRP instances of [Cordeau and Laporte, 2001] with up to 216 customers
- ▶ Solved 56/96 “nightmare” HFVRP instances of [Duhamel et al., 2011] with up to 186 customers.

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Cordeau, J.-F., Gendreau, M., and Laporte, G. (1997).

A tabu search heuristic for periodic and multi-depot vehicle routing problems.

Networks, 30(2):105–119.



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Computers and Operations Research, 39(9):2033 – 2050.



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Computers and Operations Research, 38(4):723 – 739.



Gehring, H. and Homberger, J. (2002).

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Journal of Heuristics, 8(3):251–276.



Irnich, S., Desaulniers, G., Desrosiers, J., and Hadjar, A. (2010).

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European Journal of Operational Research, 221(2):285 – 295.



Taillard, E. D. (1999).

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